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Telecommunications Hypernetwork and Telecommunications SuperHypernetwork

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Abstract


A hypergraph generalizes the classical notion of a graph by allowing edges—called hyperedges—to connect more than two vertices simultaneously. A superhypergraph further extends this idea by introducing recursively nested powerset layers, thus enabling hierarchical and self-referential relationships among hyperedges. Graphs are widely used to represent networks. In this context, hypernetworks and superhypernetworks serve as the network analogues of hypergraphs and superhypergraphs, respectively.

In this paper, we focus on the concept of the Telecommunications Network. A Telecommunications Network enables the transmission of data, voice, and video among devices using wired or wireless communication technologies. We further examine the mathematical definitions, structural properties, and real-world examples of the *Telecommunications HyperNetwork* and the *Telecommunications SuperHyperNetwork*, which extend the classical Telecommunications Network to higher-order and hierarchical communication models.

Keywords: Superhypergraph, Hypergraph, Hypernetworks, Superhypernetworks, Telecommunications Network.

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1|Preliminaries

This section provides an overview of the fundamental concepts and definitions essential for the discussions in this paper. Throughout this paper, we consider only finite structures. Unless otherwise specified, all graphs are assumed to be simple, i.e., without multiple edges. For more detailed explanations and operational procedures, the reader is encouraged to consult the relevant references as needed.

1.1|SuperHyperGraph

We begin by presenting the definitions of Graph, HyperGraph, and SuperHyperGraph. In classical graph theory [1, 2], a hypergraph generalizes a traditional graph by allowing edges—called hyperedges—to connect more than two vertices [3]. This generalization enables the modeling of more complex relationships among elements, making hypergraphs highly applicable in diverse fields [4, 5, 6]. A *SuperHyperGraph* is a more advanced extension of the hypergraph model that incorporates recursively defined powerset structures into the conventional framework. This concept has been recently introduced and widely investigated in the literature [7, 8, 9, 10]. The formal definition is provided below. Unless otherwise noted, we assume throughout this paper that n is a nonnegative integer.

Definition 1.1 (Base Set). A *base set* S is the foundational set from which complex structures such as powersets and hyperstructures are derived. It is formally defined as:

$$S = \{x \mid x \text{ is an element within a specified domain}\}.$$

All elements in constructs like $\mathcal{P}(S)$ or $\mathcal{P}_n(S)$ originate from the elements of S .

Definition 1.2 (Powerset). The *powerset* of a set S , denoted $\mathcal{P}(S)$, is the collection of all possible subsets of S , including both the empty set and S itself. Formally, it is expressed as:

$$\mathcal{P}(S) = \{A \mid A \subseteq S\}.$$

Definition 1.3 (n -th Powerset). (cf.[11])

The n -th powerset of a set H , denoted $P_n(H)$, is defined iteratively, starting with the standard powerset. The recursive construction is given by:

$$P_1(H) = P(H), \quad P_{n+1}(H) = P(P_n(H)), \quad \text{for } n \geq 1.$$

Similarly, the n -th non-empty powerset, denoted $P_n^*(H)$, is defined recursively as:

$$P_1^*(H) = P^*(H), \quad P_{n+1}^*(H) = P^*(P_n^*(H)).$$

Here, $P^*(H)$ represents the powerset of H with the empty set removed.

Definition 1.4 (Hypergraph). [12, 3] A *hypergraph* $H = (V(H), E(H))$ consists of:

- A nonempty set $V(H)$ of vertices.
- A set $E(H)$ of hyperedges, where each hyperedge is a nonempty subset of $V(H)$, thereby allowing connections among multiple vertices.

Unlike standard graphs, hypergraphs are well-suited to represent higher-order relationships. In this paper, we restrict ourselves to the case where both $V(H)$ and $E(H)$ are finite.

Definition 1.5 (n -SuperHyperGraph). [13]

Let V_0 be a finite base set of vertices. For each integer $k \geq 0$, define the iterative powerset by

$$\mathcal{P}^0(V_0) = V_0, \quad \mathcal{P}^{k+1}(V_0) = \mathcal{P}(\mathcal{P}^k(V_0)),$$

where $\mathcal{P}(\cdot)$ denotes the usual powerset operation. An *n -SuperHyperGraph* is then a pair

$$\text{SHT}^{(n)} = (V, E),$$

with

$$V \subseteq \mathcal{P}^n(V_0) \quad \text{and} \quad E \subseteq \mathcal{P}^n(V_0).$$

Each element of V is called an n -*supervertex* and each element of E an n -*superedge*.

Example 1.6 (2-SuperHyperGraph in a Telecommunications Setting). Consider a small telecommunications operator with four individual base stations:

$$V_0 = \{B_1, B_2, B_3, B_4\},$$

where each B_i denotes a distinct cellular or microwave tower. We wish to model hierarchical groupings of these base stations up to two levels (i.e. $n = 2$).

Level 1 (Clusters of Base Stations). First, form two clusters of base stations based on geographic proximity or functional role:

$$C_1 = \{B_1, B_2\}, \quad C_2 = \{B_3, B_4\}.$$

Each C_j is itself an element of the powerset $\mathcal{P}(V_0)$. These clusters might represent, for example, the group of towers serving ‘‘Downtown’’ (C_1) and the group serving ‘‘Suburban’’ (C_2).

Level 2 (Regions as Sets of Clusters). Next, form two distinct 2 -*supervertices* (i.e. elements of $\mathcal{P}^2(V_0)$) by grouping the clusters:

$$R_1 = \{C_1, C_2\}, \quad R_2 = \{C_1\}.$$

Here:

- $R_1 \in \mathcal{P}^2(V_0)$ is the ‘‘Metro Region’’ automatically combining both clusters C_1 and C_2 .
- $R_2 \in \mathcal{P}^2(V_0)$ is the ‘‘Core Subregion’’ containing only cluster C_1 .

Thus our set of 2-supervertices is

$$V = \{R_1, R_2\} \subseteq \mathcal{P}^2(V_0).$$

Superedges Between Regions. Finally, we define a collection of 2 -*superedges* $E \subseteq \mathcal{P}^2(V_0)$. For instance:

$$E_1 = \{R_1, R_2\}, \quad E_2 = \{R_1\}.$$

Explicitly,

$$E = \{E_1, E_2\}, \quad E_1 = \{\{C_1, C_2\}, \{C_1\}\}, \quad E_2 = \{\{C_1, C_2\}\}.$$

Each superedge E_k is itself a subset of $\mathcal{P}^2(V_0)$. In practical terms:

- $E_1 = \{R_1, R_2\}$ models a service linkage or inter-regional backhaul that connects the full Metro Region R_1 with its Core Subregion R_2 .
- $E_2 = \{R_1\}$ represents an internal traffic-aggregation or monitoring relationship confined to the Metro Region R_1 alone.

Interpretation in Telecommunications.

- At the *base level* (V_0), each B_i is a physical tower serving end-users.
- At *Level 1*, each cluster C_j groups nearby towers for local load balancing or frequency coordination. For example, $C_1 = \{B_1, B_2\}$ might share a local routing hub.
- At *Level 2*, each 2-supervertex R_ℓ represents a higher-level administrative or operational region. For instance, $R_1 = \{C_1, C_2\}$ is the entire metropolitan service area, while $R_2 = \{C_1\}$ is the inner downtown zone.
- A superedge like $E_1 = \{R_1, R_2\}$ can model a dedicated backhaul link or guaranteed-quality service path between the downtown zone R_2 and the larger metro region R_1 . Likewise, $E_2 = \{R_1\}$ might indicate an internal monitoring or multicast relationship confined to the metro-wide infrastructure.

Thus,

$$\text{SHT}^{(2)} = (V, E)$$

with

$$V = \{R_1, R_2\}, \quad E = \{\{R_1, R_2\}, \{R_1\}\},$$

constitutes a concrete 2-SuperHyperGraph that captures two levels of hierarchy—clusters of towers and regions containing those clusters—together with service-link relationships among them.

1.2|HyperNetwork and SuperhyperNetwork

A hypernetwork connects nodes via hyperedges, enabling multi-node interactions and weighted attributes for complex relationships. A superhypernetwork uses n -level nested sets as nodes and hyperedges, capturing hierarchical groupings and weighted associations. The definitions of HyperNetwork and SuperhyperNetwork are presented below (cf.[14]).

Definition 1.7 (Hypernetwork). (cf.[14]) A *hypernetwork* is an ordered triple

$$H = (V, \mathcal{E}, w)$$

where

- V is a nonempty finite set of *nodes*;
- $\mathcal{E} \subseteq \mathcal{P}(V) \setminus \{\emptyset\}$ is the set of *hyperedges*, each hyperedge $e \in \mathcal{E}$ being a nonempty subset of nodes (allowing multi-node interactions);
- $w: \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ is a *weight or attribute function* on hyperedges (omitted if unweighted).

A *directed hypernetwork* may be defined by replacing $\mathcal{E} \subseteq \mathcal{P}(V)$ with a set of *ordered* tuples of nodes or by equipping each $e \in \mathcal{E}$ with a head-tail partition. One can further add a *node-labeling* $\ell_V: V \rightarrow L_V$ and a *hyperedge-labeling* $\ell_{\mathcal{E}}: \mathcal{E} \rightarrow L_{\mathcal{E}}$ to record types or properties.

Definition 1.8 (n -SuperHypernetwork). (cf.[14]) Let V_0 be a finite base set of *nodes*. Define the n -th iterated powerset recursively by

$$\mathcal{P}^0(V_0) = V_0, \quad \mathcal{P}^{k+1}(V_0) = \mathcal{P}(\mathcal{P}^k(V_0)) \quad (k \geq 0).$$

An n -*superhypernetwork* is a tuple

$$\mathcal{N}^{(n)} = (V, \mathcal{E}, w)$$

where

- $V \subseteq \mathcal{P}^n(V_0)$ is a finite set of n -*supernodes*;
- $\mathcal{E} \subseteq \mathcal{P}^n(V_0)$ is a finite set of n -*superedges*, each superedge $e \in \mathcal{E}$ being a nonempty subset of V ;
- $w: \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ is an optional *weight function* assigning a nonnegative real weight (or confidence) to each superedge.

In other words, both vertices and hyperedges of the network are drawn from the n -th powerset of the base node set, capturing up to n levels of hierarchical grouping.

Example 1.9 (2-SuperHypernetwork in a Telecommunications Infrastructure). Consider a simplified telecommunications operator with four base network devices:

$$V_0 = \{D_1, D_2, D_3, D_4\},$$

where each D_i represents an individual network element (e.g., a router or switch). We construct a 2-superhypernetwork $\mathcal{N}^{(2)} = (V, \mathcal{E}, w)$ to capture two levels of hierarchical grouping: devices \rightarrow subnets \rightarrow regions.

Level 1 (Subnets as 1-Supernodes). Form two subnets (each a subset of V_0) based on logical or geographic segmentation:

$$S_1 = \{D_1, D_2\}, \quad S_2 = \{D_3, D_4\}.$$

Clearly, $S_1, S_2 \in \mathcal{P}(V_0)$. These subnets might correspond to, for instance, a “North Campus” LAN (S_1) and a “South Campus” LAN (S_2).

Level 2 (Regions as 2-Supernodes). Next, group these subnets into two higher-level regions (elements of $\mathcal{P}^2(V_0)$):

$$R_A = \{S_1, S_2\}, \quad R_B = \{S_1\}.$$

Here:

- $R_A = \{S_1, S_2\} \in \mathcal{P}^2(V_0)$ represents the entire operator’s metropolitan backbone, comprising both subnets S_1 and S_2 .
- $R_B = \{S_1\} \in \mathcal{P}^2(V_0)$ represents a focused “North Campus Region” covering only subnet S_1 .

Thus the set of 2-supernodes is

$$V = \{R_A, R_B\} \subseteq \mathcal{P}^2(V_0).$$

2-Superedges Among Regions. We now define a collection of 2-superedges $\mathcal{E} \subseteq \mathcal{P}^2(V_0)$. For example:

$$E_1 = \{R_A, R_B\}, \quad E_2 = \{R_A\}.$$

Explicitly,

$$\mathcal{E} = \{E_1, E_2\}, \quad E_1 = \{\{S_1, S_2\}, \{S_1\}\}, \quad E_2 = \{\{S_1, S_2\}\}.$$

Each E_k is itself an element of $\mathcal{P}^2(V_0)$, i.e. a subset of the set of 2-supernodes V .

Weight Function (Link Capacity). Define the weight function $w: \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ to represent, for instance, the aggregate inter-region bandwidth (in Gbps) or reliability metric:

$$w(E_1) = 10, \quad w(E_2) = 5.$$

Here:

- $w(E_1) = 10$ Gbps indicates a high-capacity backhaul link between the full metropolitan backbone R_A and its “North Campus” sub-region R_B .
- $w(E_2) = 5$ Gbps represents an internal monitoring or multicast channel that exists only within the metropolitan backbone R_A itself.

Interpretation in a Real-World Operator Network.

- At the *base level* $V_0 = \{D_1, D_2, D_3, D_4\}$, each D_i is a physical network device (e.g., edge router or switch) serving end users.
- At *Level 1*, each 1-supernode $S_j \in \{S_1, S_2\}$ is a logical subnet grouping devices for local traffic aggregation, firewall enforcement, or VLAN segmentation.
- At *Level 2*, each 2-supernode $R_\ell \in \{R_A, R_B\}$ represents a higher-level region or data center cluster. For instance, R_A models the entire metropolitan network region, while R_B isolates the North Campus region for specialized services (e.g., research labs, enterprise customers).
- The 2-superedge $E_1 = \{R_A, R_B\}$ models a primary backbone circuit that carries aggregated traffic from the North Campus region R_B into the broader metropolitan backbone R_A . Its weight $w(E_1) = 10$ Gbps reflects the capacity of that circuit.
- The 2-superedge $E_2 = \{R_A\}$ indicates an internal redundancy or multicast-streaming relationship confined solely to R_A . Its weight $w(E_2) = 5$ Gbps could represent an intra-region synchronization channel or backup link capacity.

In summary, the 2-superhypernetwork

$$\mathcal{N}^{(2)} = (V, \mathcal{E}, w), \quad V = \{R_A, R_B\}, \quad \mathcal{E} = \{E_1, E_2\}, \quad w(E_1) = 10, \quad w(E_2) = 5,$$

captures two hierarchical levels—subnets S_j and regions R_ℓ —along with weighted 2-superedges that encode high-level connectivity and capacity across the operator’s network infrastructure.

2|Results of This Paper

This section presents and explains the main results of this paper. Specifically, we examine the concepts of Telecommunications Network, Telecommunications HyperNetwork, and Telecommunications SuperHyperNetwork in detail.

2.1|Telecommunications Network

A Telecommunications Network enables the transmission of data, voice, and video among devices using wired or wireless communication technologies (cf.[15, 16, 17, 18, 19]). In this paper, we attempt to provide a formal mathematical definition of a Telecommunications Network, as described below. Please note that this is merely one example of a possible definition and does not claim to cover all real-world scenarios exhaustively.

Definition 2.1 (Telecommunications Network). A *telecommunications network* is a quadruple

$$\mathcal{N} = (V, E, \kappa, \delta),$$

where

- V is a finite set of *nodes* (e.g. switches, routers, terminals);
- $E \subseteq V \times V$ is a set of directed *links*;
- $\kappa: E \rightarrow \mathbb{R}_{>0}$ is a *capacity function*, assigning to each link $(u, v) \in E$ its maximum data-rate $\kappa(u, v)$;
- $\delta: E \rightarrow \mathbb{R}_{\geq 0}$ is a *delay function*, assigning to each link $(u, v) \in E$ its propagation or transmission delay $\delta(u, v)$.

Moreover, given a set of traffic demands $\mathcal{D} = \{(s_i, t_i, d_i) \mid s_i, t_i \in V, d_i \in \mathbb{R}_{>0}\}$, a *routing* is a collection of flows $f_i: E \rightarrow \mathbb{R}_{\geq 0}$ satisfying:

$$\sum_{(u,v) \in E} f_i(u, v) - \sum_{(v,w) \in E} f_i(v, w) = \begin{cases} d_i, & v = s_i, \\ -d_i, & v = t_i, \\ 0, & \text{otherwise,} \end{cases} \quad \forall v \in V,$$

and the *capacity constraints*

$$\sum_i f_i(u, v) \leq \kappa(u, v) \quad \forall (u, v) \in E.$$

Example 2.2 (Telecommunications Network). Consider a simple telecommunications network with three nodes:

$$V = \{A, B, C\},$$

where:

- A is a source switch,
- B is an intermediate router,
- C is a destination terminal.

The directed links E and their associated capacity κ and delay δ functions are given by:

$$E = \{(A, B), (A, C), (B, C)\},$$

with

$$\begin{aligned} \kappa(A, B) &= 100 \text{ (Mbps)}, & \delta(A, B) &= 2 \text{ (ms)}, \\ \kappa(A, C) &= 50 \text{ (Mbps)}, & \delta(A, C) &= 5 \text{ (ms)}, \\ \kappa(B, C) &= 80 \text{ (Mbps)}, & \delta(B, C) &= 1 \text{ (ms)}. \end{aligned}$$

Thus, the capacity function $\kappa: E \rightarrow \mathbb{R}_{>0}$ and delay function $\delta: E \rightarrow \mathbb{R}_{\geq 0}$ are explicitly:

$$\kappa(A, B) = 100, \kappa(A, C) = 50, \kappa(B, C) = 80, \quad \delta(A, B) = 2, \delta(A, C) = 5, \delta(B, C) = 1.$$

Suppose there is a single traffic demand:

$$\mathcal{D} = \{(s_1, t_1, d_1)\} = \{(A, C, 30)\},$$

meaning we wish to send $d_1 = 30$ Mbps from $s_1 = A$ to $t_1 = C$.

A possible routing consists of two flows $f_1: E \rightarrow \mathbb{R}_{\geq 0}$, split over both available paths $A \rightarrow B \rightarrow C$ and $A \rightarrow C$. For instance:

$$\begin{aligned} f_1(A, B) &= 20, & f_1(B, C) &= 20, \\ f_1(A, C) &= 10, & f_1(B, A) &= 0, & f_1(C, \cdot) &= 0. \end{aligned}$$

Here:

- Twenty Mbps of the demand travels along $A \rightarrow B \rightarrow C$:

$$f_1(A, B) = f_1(B, C) = 20,$$

and

- Ten Mbps travels directly over $A \rightarrow C$:

$$f_1(A, C) = 10.$$

This routing satisfies the flow-conservation constraints at each node $v \in V$:

$$\sum_{(u,v) \in E} f_1(u, v) - \sum_{(v,w) \in E} f_1(v, w) = \begin{cases} +30, & v = A, \\ -30, & v = C, \\ 0, & v = B, \end{cases}$$

and it also respects the capacity constraints on each link:

$$f_1(A, B) = 20 \leq \kappa(A, B) = 100, \quad f_1(A, C) = 10 \leq \kappa(A, C) = 50, \quad f_1(B, C) = 20 \leq \kappa(B, C) = 80.$$

Finally, the total end-to-end delay for each path is:

$$\begin{aligned} \text{Path } A \rightarrow B \rightarrow C: & \quad \delta(A, B) + \delta(B, C) = 2 + 1 = 3 \text{ ms}, \\ \text{Path } A \rightarrow C: & \quad \delta(A, C) = 5 \text{ ms}. \end{aligned}$$

Hence, this concrete example illustrates a telecommunications network $\mathcal{N} = (V, E, \kappa, \delta)$, a traffic demand \mathcal{D} , and a valid routing f_1 that obeys both flow-conservation and capacity constraints, while quantifying per-link delays and overall path latency.

2.2|Telecommunications HyperNetwork

We attempt to provide a formal mathematical definition of a Telecommunications HyperNetwork, as described below.

Definition 2.3 (Telecommunications HyperNetwork). Let V be a finite set of *nodes* (e.g. routers, switches, terminals). A *telecommunications hypernetwork* is a quadruple

$$\mathcal{H} = (V, \mathcal{E}, \kappa, \delta)$$

where

- $\mathcal{E} \subseteq \mathcal{P}(V) \setminus \{\emptyset\}$ is the set of *hyperlinks*, each $e \in \mathcal{E}$ representing a multi-node communication group;
- $\kappa: \mathcal{E} \rightarrow \mathbb{R}_{>0}$ assigns to each hyperlink its *aggregate capacity* $\kappa(e)$;
- $\delta: \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ assigns to each hyperlink its *delay* $\delta(e)$.

Data flow on hyperlink e can simultaneously reach all nodes in e , modeling multicast or broadcast links in a telecommunications setting.

Example 2.4 (Enterprise Video Conferencing as a Telecommunications HyperNetwork). Video Conferencing is a technology that enables real-time audio and visual communication between people in different locations via the internet (cf.[20, 21, 22]). Consider an organization with four conference-room video endpoints:

$$V = \{\text{Room}_A, \text{Room}_B, \text{Room}_C, \text{Room}_D\}.$$

They use a multicast server to deliver a video stream simultaneously to subsets of rooms. We model this as a telecommunications hypernetwork $\mathcal{H} = (V, \mathcal{E}, \kappa, \delta)$ where the set of hyperlinks is

$$\mathcal{E} = \left\{ \{\text{Server}, \text{Room}_A, \text{Room}_B\}, \{\text{Server}, \text{Room}_B, \text{Room}_C, \text{Room}_D\}, \{\text{Server}, \text{Room}_A, \text{Room}_D\} \right\},$$

each hyperlink modeling one multicast group. For example:

- $e_1 = \{\text{Server}, \text{Room}_A, \text{Room}_B\}$ is a small-group meeting link;
- $e_2 = \{\text{Server}, \text{Room}_B, \text{Room}_C, \text{Room}_D\}$ is a town-hall broadcast;
- $e_3 = \{\text{Server}, \text{Room}_A, \text{Room}_D\}$ is a two-site workshop link.

We assign capacities (in Mbps) and one-way delays (in ms):

$$\kappa(e_1) = 100, \quad \delta(e_1) = 20; \quad \kappa(e_2) = 500, \quad \delta(e_2) = 50; \quad \kappa(e_3) = 150, \quad \delta(e_3) = 25.$$

A single video stream of rate $r \leq \kappa(e_i)$ sent over hyperlink e_i reaches all rooms in e_i simultaneously, modeling real-time multicast. For instance, sending $r = 80$ Mbps over e_1 delivers the stream to Room_A and Room_B with 20 ms latency, while sending $r = 300$ Mbps over e_2 delivers to Room_B , Room_C , and Room_D with 50 ms latency.

Example 2.5 (IoT Firmware Distribution as a Telecommunications HyperNetwork). IoT Firmware is embedded software in IoT devices that controls hardware functions, connectivity, and data processing for remote communication (cf.[23, 24]). Consider an IoT deployment with a central server and four sensor clusters:

$$V = \{\text{Server}, \text{Cluster}_1, \text{Cluster}_2, \text{Cluster}_3, \text{Cluster}_4\}.$$

Firmware updates are pushed via multicast links that reach multiple clusters simultaneously. We model this as the hypernetwork $\mathcal{H} = (V, \mathcal{E}, \kappa, \delta)$ with hyperlinks

$$\mathcal{E} = \left\{ e_1 = \{\text{Server}, \text{Cluster}_1, \text{Cluster}_2\}, e_2 = \{\text{Server}, \text{Cluster}_2, \text{Cluster}_3\}, \right. \\ \left. e_3 = \{\text{Server}, \text{Cluster}_3, \text{Cluster}_4\}, e_4 = \{\text{Server}, \text{Cluster}_1, \text{Cluster}_4\} \right\}.$$

Each hyperlink e_i represents a multicast channel from the server to the indicated clusters. We assign:

$$\kappa(e_1) = 50 \text{ Mbps}, \quad \delta(e_1) = 30 \text{ ms}; \quad \kappa(e_2) = 40 \text{ Mbps}, \quad \delta(e_2) = 25 \text{ ms}; \\ \kappa(e_3) = 60 \text{ Mbps}, \quad \delta(e_3) = 35 \text{ ms}; \quad \kappa(e_4) = 30 \text{ Mbps}, \quad \delta(e_4) = 20 \text{ ms}.$$

To distribute a firmware image of size 200 Mb, the server selects a multicast link e_i with $\kappa(e_i) \geq 200$. For instance, using e_3 (capacity 60 Mbps) requires at least $\lceil 200/60 \rceil = 4$ successive transmissions, each incurring a 35 ms delay, to update Cluster_3 and Cluster_4 . Alternatively, one can split targets: first send via e_1 to clusters 1 and 2, then via e_3 for clusters 3 and 4. This hypernetwork model enables optimized selection of multicast groups to balance capacity constraints and delay.

Theorem 2.6 (Generalization of Telecommunications Network). *Every classical telecommunications network $\mathcal{N} = (V, E, \kappa_2, \delta_2)$, where $E \subseteq V \times V$, embeds into a telecommunications hypernetwork $\mathcal{H} = (V, \mathcal{E}, \kappa, \delta)$ by*

$$\mathcal{E} = \left\{ \{u, v\} : (u, v) \in E \right\}, \quad \kappa(\{u, v\}) = \kappa_2(u, v), \quad \delta(\{u, v\}) = \delta_2(u, v).$$

Proof: Define a mapping $\phi: E \rightarrow \mathcal{E}$ by $\phi((u, v)) = \{u, v\}$. Since each pair $\{u, v\}$ is nonempty and distinct, $\mathcal{E} \subseteq \mathcal{P}(V) \setminus \{\emptyset\}$. Setting $\kappa(\{u, v\}) = \kappa_2(u, v)$ and $\delta(\{u, v\}) = \delta_2(u, v)$ preserves capacities and delays. Thus \mathcal{N} is realized as the special case of \mathcal{H} in which all hyperlinks have cardinality two. \square

Theorem 2.7 (HyperNetwork Structure). *A telecommunications hypernetwork $\mathcal{H} = (V, \mathcal{E}, \kappa, \delta)$ carries the structure of a hypernetwork in the sense of Definition 2.7: the pair (V, \mathcal{E}) is a hypergraph on which we have added weight functions κ, δ .*

Proof: By construction, $\mathcal{E} \subseteq \mathcal{P}(V) \setminus \{\emptyset\}$, so (V, \mathcal{E}) is a hypergraph. The functions κ and δ assign nonnegative real weights to each hyperedge. Hence \mathcal{H} is precisely a weighted hypernetwork as per Definition 2.7. \square

Theorem 2.8 (Routing via Hyperlinks). *In a telecommunications hypernetwork $\mathcal{H} = (V, \mathcal{E}, \kappa, \delta)$, any traffic demand (S, T, d) with $S, T \subseteq V$ can be satisfied by flows $f: \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ satisfying*

$$\sum_{e \ni v} f(e) - \sum_{e \ni v} f(e) = \begin{cases} d, & v \in S, \\ -d, & v \in T, \\ 0, & \text{otherwise,} \end{cases}$$

subject to capacity constraints $\sum_{S, T \subseteq e} f(e) \leq \kappa(e)$.

Proof: One treats each hyperedge e as a shared multicast link: flow $f(e)$ leaves any source node in $S \cap e$ and is received by all sink nodes in $T \cap e$. By enforcing the flow-conservation balances above and ensuring $\sum_e f(e) \leq \kappa(e)$, one generalizes classical max-flow formulations to the hypernetwork setting. \square

Theorem 2.9 (Delay Aggregation). *For any path of hyperlinks e_1, e_2, \dots, e_k with $e_i \cap e_{i+1} \neq \emptyset$, the end-to-end delay satisfies*

$$\Delta = \sum_{i=1}^k \delta(e_i).$$

Proof: Because a data packet traverses each hyperlink e_i in sequence, accumulating delay $\delta(e_i)$, the total delay is the sum. Overlaps $e_i \cap e_{i+1}$ ensure connectivity of the path. \square

2.3 | Telecommunications n-SuperHyperNetwork

We attempt to provide a formal mathematical definition of a Telecommunications n-SuperHyperNetwork, as described below.

Definition 2.10 (Telecommunications n-SuperHyperNetwork). Let V_0 be a finite set of *nodes* (e.g. routers, switches, terminals). For a fixed integer $n \geq 1$, let

$$\mathcal{P}^n(V_0) = \underbrace{\mathcal{P}(\mathcal{P}(\dots \mathcal{P}(V_0) \dots))}_{n \text{ iterated powersets}}.$$

A *telecommunications n-superhypernetwork* is a quadruple

$$\mathcal{H}^{(n)} = (V, \mathcal{E}, \kappa, \delta)$$

where

- $V \subseteq \mathcal{P}^n(V_0)$ is a finite set of *n-supernodes*;
- $\mathcal{E} \subseteq \mathcal{P}^n(V_0)$ is a finite set of *n-superhyperlinks*, each $e \in \mathcal{E}$ a nonempty subset of V ;
- $\kappa: \mathcal{E} \rightarrow \mathbb{R}_{>0}$ assigns to each superhyperlink its aggregate *capacity*;
- $\delta: \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ assigns to each superhyperlink its *delay*.

Data transmitted on a superhyperlink e reaches all contained supernodes simultaneously, modeling multicast at hierarchical levels.

Example 2.11 (Telecommunications 2-SuperHyperNetwork for Hierarchical Multicast). Hierarchical Multicast is a scalable data transmission method that organizes multicast routing in layers to efficiently distribute data across networks (cf.[25, 26, 27]). Let the base set of physical routers be

$$V_0 = \{R_1, R_2, R_3\}.$$

The first iterated powerset

$$\mathcal{P}^1(V_0) = \{\{R_1, R_2\}, \{R_1, R_3\}, \{R_2, R_3\}\}$$

represents *subnets* of two routers. The second iterated powerset

$$\mathcal{P}^2(V_0) = \mathcal{P}(\mathcal{P}^1(V_0))$$

is the set of all *clusters of subnets*. For our 2-superhypernetwork, choose the supernodes

$$V = \{C_A, C_B\} \subseteq \mathcal{P}^2(V_0),$$

where

$$C_A = \{\{R_1, R_2\}, \{R_2, R_3\}\}, \quad C_B = \{\{R_1, R_3\}, \{R_2, R_3\}\}.$$

Define two superhyperlinks in $\mathcal{E} \subseteq \mathcal{P}^2(V_0)$:

$$e_1 = \{C_A, C_B\}, \quad e_2 = \{C_A\}.$$

Assign aggregate capacities and delays by

$$\kappa(e_1) = 100 \text{ Mbps}, \quad \delta(e_1) = 40 \text{ ms}; \quad \kappa(e_2) = 50 \text{ Mbps}, \quad \delta(e_2) = 20 \text{ ms}.$$

Thus the 2-superhypernetwork $\mathcal{H}^{(2)} = (V, \mathcal{E}, \kappa, \delta)$ models:

- *Supernodes* C_A, C_B each grouping two overlapping subnets,
- *Superhyperlink* e_1 connecting both clusters for a full-network multicast,
- *Superhyperlink* e_2 servicing only cluster C_A .

A multicast stream of rate $r \leq 100$ Mbps on e_1 reaches all subnets in both clusters with 40 ms latency, while a smaller regional update of rate $r \leq 50$ Mbps can be delivered to cluster C_A alone via e_2 in 20 ms. This hierarchical setup captures multicast at two levels of network grouping.

Example 2.12 (Telecommunications 3-SuperHyperNetwork for Multi-Tier IoT Update Distribution). Let the base set of edge devices be

$$V_0 = \{\text{EN}_1, \text{EN}_2, \text{EN}_3\}.$$

Then

$$\mathcal{P}^1(V_0) = \{\{\text{EN}_1, \text{EN}_2\}, \{\text{EN}_1, \text{EN}_3\}, \{\text{EN}_2, \text{EN}_3\}\},$$

representing *local subnets*. Next,

$$\mathcal{P}^2(V_0) = \mathcal{P}(\mathcal{P}^1(V_0))$$

is the set of *regional clusters* of subnets. Choose three clusters:

$$R_A = \{\{\text{EN}_1, \text{EN}_2\}, \{\text{EN}_2, \text{EN}_3\}\}, \quad R_B = \{\{\text{EN}_1, \text{EN}_3\}, \{\text{EN}_2, \text{EN}_3\}\}, \quad R_C = \{\{\text{EN}_1, \text{EN}_2\}, \{\text{EN}_1, \text{EN}_3\}\}.$$

Finally,

$$\mathcal{P}^3(V_0) = \mathcal{P}(\mathcal{P}^2(V_0))$$

is the set of *global divisions* of regional clusters. We define two supernodes:

$$G_1 = \{R_A, R_B\}, \quad G_2 = \{R_B, R_C\}.$$

Thus our 3-superhypernetwork is $\mathcal{H}^{(3)} = (V, \mathcal{E}, \kappa, \delta)$ with

$$V = \{G_1, G_2\} \subseteq \mathcal{P}^3(V_0),$$

and two superhyperlinks:

$$e_1 = \{G_1, G_2\}, \quad e_2 = \{G_1\}.$$

Assign aggregate capacities and delays:

$$\kappa(e_1) = 10 \text{ Gbps}, \quad \delta(e_1) = 100 \text{ ms}; \quad \kappa(e_2) = 4 \text{ Gbps}, \quad \delta(e_2) = 40 \text{ ms}.$$

A firmware image of size 2 GB can be multicast globally via e_1 in a single transmission (provided $2 \text{ GB} \leq 10 \text{ Gbps}$ within the delay bound of 100 ms), reaching all devices in both divisions G_1 and G_2 . Alternatively, a smaller patch of size 1 GB can be sent to division G_1 alone via e_2 , leveraging its 40 ms latency. This hierarchical 3-superhypernetwork model captures multi-tier multicast distribution across local subnets, regional clusters, and global divisions.

Example 2.13 (Telecommunications 3-SuperHyperNetwork for Global CDN Hierarchy). Let the base set of Points of Presence (PoPs [28]) be

$$V_0 = \{\text{POP}_{\text{NY}}, \text{POP}_{\text{LA}}, \text{POP}_{\text{LDN}}\}.$$

Then

$$\mathcal{P}^1(V_0) = \{\{\text{POP}_{\text{NY}}, \text{POP}_{\text{LA}}\}, \{\text{POP}_{\text{NY}}, \text{POP}_{\text{LDN}}\}, \{\text{POP}_{\text{LA}}, \text{POP}_{\text{LDN}}\}\}$$

represents *metro clusters*. Next,

$$\mathcal{P}^2(V_0) = \mathcal{P}(\mathcal{P}^1(V_0))$$

is the set of *regional clusters* of metro clusters. Choose two:

$$R_{\text{Americas}} = \{\{\text{POP}_{\text{NY}}, \text{POP}_{\text{LA}}\}, \{\text{POP}_{\text{LA}}, \text{POP}_{\text{LDN}}\}\}, \quad R_{\text{EMEA}} = \{\{\text{POP}_{\text{NY}}, \text{POP}_{\text{LDN}}\}, \{\text{POP}_{\text{LA}}, \text{POP}_{\text{LDN}}\}\}.$$

Finally,

$$\mathcal{P}^3(V_0) = \mathcal{P}(\mathcal{P}^2(V_0))$$

is the set of *global divisions* of regional clusters. Define two supernodes:

$$G_{\text{Primary}} = \{R_{\text{Americas}}, R_{\text{EMEA}}\}, \quad G_{\text{Backup}} = \{R_{\text{EMEA}}\}.$$

Thus our 3-superhypernetwork is $\mathcal{H}^{(3)} = (V, \mathcal{E}, \kappa, \delta)$ with

$$V = \{G_{\text{Primary}}, G_{\text{Backup}}\} \subseteq \mathcal{P}^3(V_0),$$

and two superhyperlinks:

$$e_1 = \{G_{\text{Primary}}, G_{\text{Backup}}\}, \quad e_2 = \{G_{\text{Primary}}\}.$$

Assign aggregate capacities (in Tbps) and delays (in ms):

$$\kappa(e_1) = 5, \quad \delta(e_1) = 150; \quad \kappa(e_2) = 2, \quad \delta(e_2) = 80.$$

A high-volume content distribution session (e.g. live video) of rate up to 5 Tbps sent over e_1 reaches both primary and backup divisions with 150 ms end-to-end latency. A lower-priority but latency-sensitive update (rate ≤ 2 Tbps) can be delivered exclusively to the primary division via e_2 in 80 ms. This hierarchical model captures global CDN routing across metro clusters, regional clusters, and global divisions.

Theorem 2.14 (Generalization of Classical Telecommunications Networks). *Every classical telecommunications network $\mathcal{N} = (V_0, E_0, \kappa_0, \delta_0)$, with $E_0 \subseteq V_0 \times V_0$, embeds into a telecommunications n -superhypernetwork $\mathcal{H}^{(n)}$ by*

$$V = \{\eta_n(v) : v \in V_0\}, \quad \mathcal{E} = \{\{\eta_n(u), \eta_n(v)\} : (u, v) \in E_0\},$$

and

$$\kappa(\{\eta_n(u), \eta_n(v)\}) = \kappa_0(u, v), \quad \delta(\{\eta_n(u), \eta_n(v)\}) = \delta_0(u, v),$$

where $\eta_n(x)$ denotes the n -fold nested singleton $\{\{\dots\{x\}\dots\}\}$.

Proof: Define $\eta_n : V_0 \rightarrow \mathcal{P}^n(V_0)$ by $\eta_1(x) = \{x\}$ and $\eta_{k+1}(x) = \{\eta_k(x)\}$. Then each original node v becomes an n -supernode $\eta_n(v)$, and each original link (u, v) becomes the superhyperlink $\{\eta_n(u), \eta_n(v)\}$. By construction $\mathcal{E} \subseteq \mathcal{P}^n(V_0)$ and capacity/delay assignments agree. Hence \mathcal{N} is realized as the special case of $\mathcal{H}^{(n)}$ with all superhyperlinks of size two. \square

Theorem 2.15 (Generalization of Telecommunications HyperNetworks). *Every telecommunications hypernetwork $\mathcal{H} = (V_1, \mathcal{E}_1, \kappa_1, \delta_1)$ embeds into an n -superhypernetwork $\mathcal{H}^{(n)}$ by*

$$V = \{\eta_n(v) : v \in V_1\}, \quad \mathcal{E} = \{\{\eta_n(e) : e \in E\} : E \in \mathcal{E}_1\},$$

with weights $\kappa(\{\eta_n(e) : e \in E\}) = \kappa_1(E)$ and $\delta(\{\eta_n(e) : e \in E\}) = \delta_1(E)$.

Proof: Let η_n be as above extended to subsets of V_1 by $\eta_n(E) = \{\eta_n(v) : v \in E\}$. Then each hyperedge $E \subseteq V_1$ maps to an n -superhyperlink $\eta_n(E) \subseteq \mathcal{P}^n(V_0)$. Capacities and delays transfer accordingly. Thus \mathcal{H} embeds into $\mathcal{H}^{(n)}$. \square

Theorem 2.16 (n -SuperHyperNetwork Structure). *A telecommunications n -superhypernetwork $\mathcal{H}^{(n)} = (V, \mathcal{E}, \kappa, \delta)$ is an n -superhyperstructure on the base set V_0 : its supernodes and superhyperlinks are drawn from $\mathcal{P}^n(V_0)$, and the capacity/delay functions endow it with weighted superhypergraph structure.*

Proof: By definition, $V, \mathcal{E} \subseteq \mathcal{P}^n(V_0)$. The pair (V, \mathcal{E}) thus forms an n -superhypergraph, and κ, δ provide weights. Hence $\mathcal{H}^{(n)}$ satisfies the structure of an n -superhypernetwork as per Definition of n -superhypergraphs and weighted hypernetworks. \square

Theorem 2.17 (Embedding of Lower-Level SuperHypernetworks). *For each $0 \leq k \leq n$, the inclusion*

$$\iota_k: \mathcal{P}^k(V_0) \hookrightarrow \mathcal{P}^n(V_0), \quad X \mapsto \underbrace{\{\{\dots\{X\}\dots\}\}}_{n-k \text{ nestings}},$$

identifies $(\mathcal{P}^k(V_0), \mathcal{E}_k, \kappa_k, \delta_k)$ as a sub-superhypernetwork of $\mathcal{H}^{(n)}$, where $\mathcal{E}_k = \mathcal{E} \cap \iota_k(\mathcal{P}^k(V_0))$ and weights restrict accordingly.

Proof: By construction, $\iota_k(X) \in \mathcal{P}^n(V_0)$ for all $X \in \mathcal{P}^k(V_0)$. Since $\mathcal{E} \subseteq \mathcal{P}^n(V_0)$, the intersection $\mathcal{E}_k = \mathcal{E} \cap \iota_k(\mathcal{P}^k(V_0))$ consists exactly of those n -superhyperlinks that arise from k -level objects. Restricting κ, δ to \mathcal{E}_k makes $(\iota_k(\mathcal{P}^k(V_0)), \mathcal{E}_k, \kappa|_{\mathcal{E}_k}, \delta|_{\mathcal{E}_k})$ itself an n -superhypernetwork. Because ι_k is injective and respects the nested-powerset structure, this copy is isomorphic to the k -superhypernetwork on $\mathcal{P}^k(V_0)$. \square

Theorem 2.18 (Flattening to a HyperNetwork). *There is a natural “flattening” map*

$$\pi: \mathcal{P}^n(V_0) \longrightarrow \mathcal{P}(V_0),$$

defined by iterated union $\pi(X) = \bigcup(\dots \bigcup X \dots)$. Under π , \mathcal{E} is sent to a set of hyperedges in $\mathcal{P}(V_0)$, and $(V_0, \pi(\mathcal{E}), \kappa \circ \pi^{-1}, \delta \circ \pi^{-1})$ is a telecommunications hypernetwork.

Proof: Define π by $\pi_1(Y) = Y$ for $Y \subseteq V_0$ and $\pi_{k+1}(X) = \bigcup_{Y \in X} \pi_k(Y)$. Then $\pi = \pi_n$ maps each n -supernode $X \subseteq \mathcal{P}^{n-1}(V_0)$ to a subset of V_0 . The image $\pi(\mathcal{E}) \subseteq \mathcal{P}(V_0)$ thus gives a set of hyperedges. Assigning capacities and delays by $\kappa'(e) = \sum_{E: \pi(E)=e} \kappa(E)$ and similarly for δ yields a weighted hypernetwork. Closure and weight-assignment verification are straightforward. \square

Theorem 2.19 (Union of SuperHypernetworks). *If $\mathcal{H}_1^{(n)} = (V_1, \mathcal{E}_1, \kappa_1, \delta_1)$ and $\mathcal{H}_2^{(n)} = (V_2, \mathcal{E}_2, \kappa_2, \delta_2)$ are two n -superhypernetworks on the same base V_0 , then their union*

$$\mathcal{H}_{\cup}^{(n)} = (V_1 \cup V_2, \mathcal{E}_1 \cup \mathcal{E}_2, \kappa_{\cup}, \delta_{\cup})$$

is also a telecommunications n -superhypernetwork, where $\kappa_{\cup}, \delta_{\cup}$ extend κ_i, δ_i by taking maximum weights on overlaps.

Proof: Since $V_1, V_2 \subseteq \mathcal{P}^n(V_0)$ and $\mathcal{E}_1, \mathcal{E}_2 \subseteq \mathcal{P}^n(V_0)$, their unions remain subsets of $\mathcal{P}^n(V_0)$. Defining $\kappa_{\cup}(E) = \max\{\kappa_1(E), \kappa_2(E)\}$ for $E \in \mathcal{E}_1 \cap \mathcal{E}_2$, and similarly for δ , ensures each superhyperlink has a well-defined capacity and delay. Hence $\mathcal{H}_{\cup}^{(n)}$ satisfies Definition 4.1. \square

Theorem 2.20 (Connectivity Preservation). *If the base network $\mathcal{N} = (V_0, E_0)$ is connected, then the induced n -superhypernetwork $\mathcal{H}^{(n)}$ is connected in the sense that for any two supernodes $X, Y \in V$, there exists a sequence of superhyperlinks*

$$E_1, E_2, \dots, E_k \in \mathcal{E}$$

such that $X \cap E_1 \neq \emptyset$, $E_i \cap E_{i+1} \neq \emptyset$, and $E_k \cap Y \neq \emptyset$.

Proof: Connectivity of \mathcal{N} means for any $u, v \in V_0$ there is a path $u = v_0, v_1, \dots, v_m = v$ with $\{v_i, v_{i+1}\} \in E_0$. Under the embedding of Theorem 4.2, each node v_i lifts to a supernode $\eta_n(v_i)$ and each link $\{v_i, v_{i+1}\}$ to the superhyperlink $\{\eta_n(v_i), \eta_n(v_{i+1})\}$. These form a chain of superhyperlinks connecting $\eta_n(u)$ to $\eta_n(v)$. For arbitrary $X, Y \subseteq \mathcal{P}^n(V_0)$, pick $u \in \pi(X)$ and $v \in \pi(Y)$. The above yields a superpath between $\eta_n(u)$ and $\eta_n(v)$. Since $X \cap \{\eta_n(u)\} \neq \emptyset$ and $\{\eta_n(v)\} \cap Y \neq \emptyset$, concatenation gives the desired connectivity. \square

Remark 2.21. Let V_0 be a finite base node set and write

$$\mathcal{P}^n(V_0) = \underbrace{\mathcal{P}(\mathcal{P}(\cdots \mathcal{P}(V_0) \cdots))}_{n \text{ times}}.$$

Suppose $\mathcal{H}^{(n)} = (V, \mathcal{E}, \kappa, \delta)$ is a telecommunications n -superhypernetwork, and define the *flattening map*

$$\pi : \mathcal{P}^n(V_0) \longrightarrow \mathcal{P}(V_0) \quad \text{by} \quad \pi_1(S') = S', \quad \pi_{k+1}(X) = \bigcup_{Y \in X} \pi_k(Y),$$

so that $\pi = \pi_n$.

Theorem 2.22 (Embedding–Flattening Retraction). *Let $\eta_n : V_0 \rightarrow \mathcal{P}^n(V_0)$ be the n -fold singleton embedding defined by $\eta_1(v) = \{v\}$ and $\eta_{k+1}(v) = \{\eta_k(v)\}$. Then*

$$\pi \circ \eta_n = \text{id}_{V_0}.$$

Proof: By induction on k . For $k = 1$, $\pi_1(\eta_1(v)) = \pi_1(\{v\}) = \{v\}$. Since π_1 on singletons is the identity on subsets of V_0 , and $\pi_{k+1}(\{\eta_k(v)\}) = \pi_k(\eta_k(v))$ by definition of π , the composition $\pi_{k+1} \circ \eta_{k+1}(v) = \pi_k(\eta_k(v))$. By the induction hypothesis $\pi_k \circ \eta_k(v) = v$. Hence $\pi \circ \eta_n(v) = v$ for all $v \in V_0$. \square

Theorem 2.23 (Flattening Surjectivity on Hyperedges). *The flattening map π induces a surjection*

$$\pi : \mathcal{E} \longrightarrow \mathcal{E}_{\text{flat}} = \{\pi(e) : e \in \mathcal{E}\} \subseteq \mathcal{P}(V_0).$$

Proof: By definition $\mathcal{E} \subseteq \mathcal{P}^n(V_0)$. Every hyperedge in the flattened network $\mathcal{E}_{\text{flat}}$ arises as $\pi(e)$ for some $e \in \mathcal{E}$. Thus π is onto $\mathcal{E}_{\text{flat}}$. \square

Theorem 2.24 (Union and Intersection Preservation). *For any $e, f \in \mathcal{E}$,*

$$\pi(e \cup f) = \pi(e) \cup \pi(f), \quad \pi(e \cap f) = \pi(e) \cap \pi(f).$$

Proof: By the recursive definition of π , unions and intersections commute with iterated unions. Concretely, at each level k , $\pi_{k+1}(X \cup Y) = \bigcup_{Z \in X \cup Y} \pi_k(Z) = \bigcup_{Z \in X} \pi_k(Z) \cup \bigcup_{Z \in Y} \pi_k(Z) = \pi_{k+1}(X) \cup \pi_{k+1}(Y)$, and similarly for intersections. Induction on k yields the result for $k = n$. \square

Theorem 2.25 (Flow Preservation under Flattening). *Suppose $f : \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ is a feasible multicast flow in $\mathcal{H}^{(n)}$ for a demand (S, T, d) , satisfying*

$$\sum_{e \ni X} f(e) - \sum_{e \ni Y} f(e) = \begin{cases} d, & X \in S, \\ -d, & X \in T, \\ 0, & \text{otherwise,} \end{cases} \quad \sum_{e \in \mathcal{E}} f(e) \leq \kappa(e).$$

Then $f_{\text{flat}} : \mathcal{E}_{\text{flat}} \rightarrow \mathbb{R}_{\geq 0}$ defined by

$$f_{\text{flat}}(e') = \sum_{e: \pi(e)=e'} f(e)$$

is a feasible flow in the flattened hypernetwork $(V_0, \mathcal{E}_{\text{flat}}, \kappa', \delta')$ of the same demand.

Proof: For each base node $v \in V_0$, flow-conservation holds because every superhyperedge e with $\pi(e) = e'$ that contains the singleton $\eta_n(v)$ contributes $f(e)$ to both the aggregated inflow and outflow at v , mirroring the superhypernetwork balance. Capacity constraints translate as $\sum_{e': \pi(e)=e'} f_{\text{flat}}(e') = \sum_e f(e) \leq \kappa(e) \leq \kappa'(e')$ by defining $\kappa'(e') = \sum_{e: \pi(e)=e'} \kappa(e)$. Hence f_{flat} is feasible. \square

Theorem 2.26 (Minimum Cut Duality). *In the flattened hypernetwork, the value of the minimum S - T cut equals the value of the minimum cut in $\mathcal{H}^{(n)}$ under capacity aggregation:*

$$\min_{C \subseteq \mathcal{E}_{\text{flat}}} \sum_{e' \in C} \kappa'(e') = \min_{D \subseteq \mathcal{E}} \sum_{e \in D} \kappa(e).$$

Proof: Every cut $D \subseteq \mathcal{E}$ in the n -superhypernetwork induces a cut $\pi(D) \subseteq \mathcal{E}_{\text{flat}}$ in the flattened network with aggregated capacity $\sum_{e' \in \pi(D)} \kappa'(e') = \sum_{e \in D} \kappa(e)$. Conversely, any cut $C \subseteq \mathcal{E}_{\text{flat}}$ lifts to $D = \bigcup_{e' \in C} \{e : \pi(e) = e'\} \subseteq \mathcal{E}$ of the same capacity. Hence the minima coincide. \square

3|Conclusion and Future Tasks

In this paper, we examined the mathematical definitions, structural properties, and practical examples of the *Telecommunications HyperNetwork* and the *Telecommunications SuperHyperNetwork*, which extend the classical Telecommunications Network to higher-order and hierarchical communication models.

Looking ahead, we anticipate conducting computational experiments and exploring real-world applications of these models. Furthermore, we plan to investigate extensions of the concepts introduced here to other “fuzzy-style” graph frameworks, such as Fuzzy Graphs [29, 30], Intuitionistic Fuzzy Graphs [31, 32, 33], Neutrosophic Graphs [34, 35, 36, 37], and Plithogenic Graphs [38, 39].

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Ethical Approval

As this research is entirely theoretical in nature and does not involve human participants or animal subjects, no ethical approval is required.

Data Availability

This research is purely theoretical, involving no data collection or analysis. We encourage future researchers to pursue empirical investigations to further develop and validate the concepts introduced here.

Research Integrity

The authors hereby confirm that, to the best of their knowledge, this manuscript is their original work, has not been published in any other journal, and is not currently under consideration for publication elsewhere at this stage.

Disclaimer (Note on Computational Tools)

No computer-assisted proof, symbolic computation, or automated theorem proving tools (e.g., Mathematica, SageMath, Coq, etc.) were used in the development or verification of the results presented in this paper. All proofs and derivations were carried out manually and analytically by the authors.

Disclaimer (Limitations and Claims)

The theoretical concepts presented in this paper have not yet been subject to practical implementation or empirical validation. Future researchers are invited to explore these ideas in applied or experimental settings. Although every effort has been made to ensure the accuracy of the content and the proper citation of sources, unintentional errors or omissions may persist. Readers should independently verify any referenced materials.

To the best of the authors' knowledge, all mathematical statements and proofs contained herein are correct and have been thoroughly vetted. Should you identify any potential errors or ambiguities, please feel free to contact the authors for clarification.

The results presented are valid only under the specific assumptions and conditions detailed in the manuscript. Extending these findings to broader mathematical structures may require additional research. The opinions and conclusions expressed in this work are those of the authors alone and do not necessarily reflect the official positions of their affiliated institutions.

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Author has declared that no competing interests exist.

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